

# Solving Exists/Forall Problems With Yices

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## Exists/Forall Problems

### Example Synthesis Problem

- Find a function  $f$  such that  $\forall y : \Phi(y, f(y))$   
( $\Phi$  specifies the properties we want for  $f$ )

### Parameterization

- Look at a collection of functions  $f_x$  defined by a **template** parameterized by variables  $x$ .

**Example:** linear functions  $f_{a,b,c}(y_1, y_2) = a + by_1 + cy_2$

- The synthesis problem is now: find parameters  $x$  such that  $\forall y : \Phi(y, f_x(y))$   
This is an **exists/forall problem**: check the satisfiability of

$$\exists x : \forall y : \Phi(y, f_x(y))$$

## Example Application: Invariant Synthesis

### Safety Property

- Given a state-transition system, we want to show that all reachable states satisfy a property  $P(x)$
- We can try to find an inductive invariant  $Q(x)$ :

$$\forall x : I(x) \Rightarrow Q(x)$$

$$\forall x, x' : Q(x) \wedge T(x, x') \Rightarrow Q(x')$$

$$\forall x : Q(x) \Rightarrow P(x)$$

### Template-Based Method

- Postulate that  $Q(x)$  is of the form  $F_{a,b,\dots}$  for some unknown parameters  $a, b, \dots$
- Search for a solution to the following exists/forall problem:

$$\exists a, b, \dots : \forall x, x' : (I(x) \Rightarrow F_{a,b,\dots}(x))$$

$$\wedge (F_{a,b,\dots}(x) \wedge T(x, x') \Rightarrow F_{a,b,\dots}(x'))$$

$$\wedge (F_{a,b,\dots}(x) \Rightarrow P(x))$$

## More Examples

### Template-based Synthesis

- loop-free programs (Jha et al., 2011, Jha et al. 2010)
- switching logic for hybrid systems (Taly et al., 2011)
- controller synthesis (Cheng et al., 2013, Sturm and Tiwari, 2013)

### Template-based Verification

- **Lyapunov Functions:** to show stability of dynamical systems
- **Barrier Certificates for Hybrid Systems:** (Prajna, 2003, ...)

## How to Solve It?

$$\exists x : \forall y : \Phi(x, y)$$

### Quantifier-Elimination Methods

- Rewrite  $\forall y : \Phi(x, y)$  into an equivalent **quantifier-free formula**  $\Phi'(x)$
- Search for  $x$  that satisfies  $\Phi'(x)$

### Two-Solver Approach

- **E-solver**: search for candidates  $x$
- **F-solver**: given a candidate  $x_0$ , try to show it's not good:  
search for  $y$  such that  $\neg\Phi(x_0, y)$
- Repeat until we find a good candidate or we have exhausted all candidates

## Comparison/Tradeoffs

### Quantifier Elimination

- Applicable to real arithmetic (linear and non-linear), Boolean problems, etc.
- Does more than we need:  $\Phi'(x)$  characterizes all solutions, we just need one
- Typically very expensive (huge blowup in formula size)
- Requires specialized tools (e.g., CAD algorithm)

### Two Solvers

- Existing SMT or SAT solvers can be used
- Other approaches are applicable: random sampling, numerical methods
- Potentially more scalable than quantifier elimination (no immediate blow up)
- **Issues**
  - How to efficiently combine the two solvers?
  - How to guarantee termination?

## EF-Solver Algorithm

$i := 0$

$C_0(x) :=$  **initial constraints on  $x$**

repeat

    find  $x_i$  that satisfies  $C_i(x)$

[E-Solver]

    if no  $x_i$  is found, return **unsat**

    search for  $y_i$  that satisfies  $\neg\Phi(x_i, y)$

[F-Solver]

    if no  $y_i$  is found, then  $x_i$  is a solution;

    return **sat**

**generalize from  $y_i$** : compute a constraint  $G(x)$  such that

        1)  $G(x_i)$  is true

        2)  $G(x) \Rightarrow (\exists y : \neg\Phi(x, y))$

$C_{i+1}(x) := C_i(x) \wedge \neg G(x)$

$i := i + 1$

end

## Key Procedure: Generalization

### Three Methods Implemented in Yices

- **baseline:** just remove  $x_i$ :  $G(x) := (x = x_i)$
- **generalize by substitution:**  $G(x) := \neg\Phi(x, y_i)$
- **better:** local quantifier elimination
  - find an implicant  $J(x, y)$  for  $\neg\Phi(x, y)$  using  $x_i$  and  $y_i$ :
    - $J(x, y)$  is a conjunction of literals
    - $J(x, y) \Rightarrow \neg\Phi(x, y)$  holds
    - $J(x_i, y_i)$  is true
  - construct  $G(x)$  by eliminating the  $y$  variables from  $J(x, y)$



## Convergence

### Termination Guarantees

- obvious if the  $x$  variables have a finite domain
- otherwise, termination depends on the generalization procedure
  - if the  $y$  variables have a finite domain, then generalization by substitution ensures termination
  - for infinite domains: some form of quantifier elimination is required

**Example:** in linear arithmetic

$$\exists x \in \mathbb{R} : \forall y \in \mathbb{R} : x < y$$

This is unsat but EF-solving using generalization by substitution doesn't converge.

## Implicant Construction

### Goal

- given a formula  $\Phi$  and a model  $\mathcal{M}$  of  $\Phi$ , construct a conjunction of literals  $I$  such that  $I \Rightarrow \Phi$  and  $\mathcal{M} \models I$

### Procedure

- Top-down traversal of  $\Phi$ , using  $\mathcal{M}$  to guide the search.
- This relies on the fact that we can evaluate formulas in  $\mathcal{M}$ .
- Example: to find an implicant for  $(\phi_1 \vee \dots \vee \phi_n)$ ,
  - search for  $\phi_i$  that's true in  $\mathcal{M}$
  - then recursively compute an implicant of  $\phi$

## (Simplified) Implicant Construction

$$\text{Imp}^+(l) := l$$

$$\begin{aligned} \text{Imp}^+(f_1 \vee f_2) &:= \text{Imp}^+(f_1) && \text{if } f_1 \text{ is true in } \mathcal{M} \\ &:= \text{Imp}^+(f_2) && \text{otherwise} \end{aligned}$$

$$\text{Imp}^+(f_1 \wedge f_2) := \text{Imp}^+(f_1) \wedge \text{Imp}^+(f_2)$$

$$\text{Imp}^+(\neg f) := \text{Imp}^-(f)$$

$$\begin{aligned} \text{Imp}^-(t = 0) &:= (t > 0) && \text{if } t \text{ has a positive value in } \mathcal{M} \\ &:= \neg(t \geq 0) && \text{if } t \text{ has a negative value in } \mathcal{M} \end{aligned}$$

$$\text{Imp}^-(t > 0) := \neg(t > 0)$$

$$\text{Imp}^-(t \geq 0) := \neg(t \geq 0)$$

$$\text{Imp}^-(f_1 \vee f_2) := \text{Imp}^-(f_1) \wedge \text{Imp}^-(f_2)$$

$$\begin{aligned} \text{Imp}^-(f_1 \wedge f_2) &:= \text{Imp}^-(f_1) && \text{if } f_1 \text{ is false in } \mathcal{M} \\ &:= \text{Imp}^-(f_2) && \text{otherwise} \end{aligned}$$

$$\text{Imp}^-(\neg f) := \text{Imp}^+(f)$$

## Real Implicant Construction

### If-then-else

- Implicant for  $1 + (\text{ite } c \ x \ y) \geq 0$  can be either  $c \wedge 1 + x \geq 0$  or  $\neg c \wedge 1 + y \geq 0$ .

### Distinct atoms

- $(\text{distinct } t_1 \ \dots \ t_n)$  is converted to a conjunction of inequalities if  $t_1, \dots, t_n$  are arithmetic terms.
- This is done by sorting  $t_1, \dots, t_n$  according to their values in the model.

### Boolean terms

- In some contexts, we treat Booleans as terms, in other contexts we treat them as formulas.
- **Example:**
  - $(x = u)$  is treated as an atom if  $x$  is a Boolean variable
  - $(t = u)$  is treated as  $(t \wedge u) \vee (\neg t \wedge \neg u)$  if  $t$  and  $u$  are not variables

## Variable Elimination

### Goal

- We have an implicant  $J(x, y)$  that is true in a model  $\mathcal{M}$
- We want to eliminate the variables  $y$  from  $J(x, y)$
- We could try to construct a  $G(x)$  that's equivalent to  $\exists y : J(x, y)$
- In our context, it is enough to obtain an **under-approximation**:

$$G(x) \Rightarrow \exists y : J(x, y)$$

such that  $\mathcal{M} \models G(x)$

For linear (and non-linear) arithmetic, we can do this efficiently using **Model-Guided Virtual Term Substitution**

## Virtual Term Substitution for Linear Arithmetic

Weispfenning, 1988, Loos & Weispfenning, 1993

- To eliminate  $y$  from a linear arithmetic formula  $\exists y : \phi(x, y)$ , construct an **elimination set** for  $y$  in  $\phi(x, y)$
- An elimination set is a finite set  $T$  of terms that do not contain  $y$  and such that

$$(\exists y : \phi(x, y)) \Leftrightarrow \bigvee_{t \in T} \phi(x, t)$$

- $T$  can be constructed syntactically from the atoms of  $\phi$

### Example

- For  $(\exists y : 3x + 1 < y \wedge y < x + 2)$ , Weispfenning's procedure gives

$$T = \left\{ 3x, 3x + 1, 3x + 2, x + 1, x + 2, x + 3, \frac{(3x + 1) + (x + 2)}{2} \right\}$$

## Model-Guided Virtual Term Substitution

### Idea

- We start from an elimination set  $T$  such that

$$(\exists y : \phi(x, y)) \Leftrightarrow \bigvee_{t \in T} \phi(x, t)$$

- Since we can under-approximate, it's enough for us to pick a single term  $t_0$  in  $T$

$$\phi(x, t_0) \Rightarrow (\exists y : \phi(x, y))$$

- We also have a model  $\mathcal{M}$  of  $\phi(x, y)$  so we use  $\mathcal{M}$  to find a suitable  $t_0$

## Example

$$\exists y : 3x + 1 < y \wedge y < x + 2$$

$$T = \left\{ 3x, 3x + 1, 3x + 2, x + 1, x + 2, x + 3, \frac{(3x + 1) + (x + 2)}{2} \right\}$$

**Model:**  $x \mapsto 0$  and  $y \mapsto 1.5$

- We pick

$$t_0 = \frac{(3x + 1) + (x + 2)}{2}$$

then  $\phi(x, t_0)$  reduces to  $x < 1/2$



## Variable Elimination as Implemented in Yices

### Input

- The implicant construction produces a conjunction of arithmetic inequalities and equalities

### Hybrid Approach

- eliminate variables that occur in equalities (Gaussian elimination)
- use Fourier-Motzkin if it's cheap
- use virtual-term substitution as a last step.

## Other Tricks

### Preprocessing

- rewrite the problem to the following form:

$$\begin{aligned} & \exists x : A(x) \\ & \wedge (\forall y_1 : B_1(y_1) \Rightarrow \phi_1(x, y_1)) \\ & \quad \vdots \\ & \wedge (\forall y_n : B_n(y_n) \Rightarrow \phi_n(x, y_n)) \end{aligned}$$

- this tends to give smaller problem instances to the F-solver
- this helps learning the initial constraints on  $x$ :  
(i.e., we search for  $y_i$  that satisfies  $B_i(y_i)$ )

### Sampling Approach

- to find “diverse”  $y_i$ , we use a bounded variant of all-SAT

## Implementation Status

### EF Solver

- Part of Yices since version 2.3.
- Available at <http://yices.csl.sri.com/>
  - The EF solver supports linear real arithmetic, bitvector, and Boolean constraints
  - The input must be given in the Yices language
  - Generalization and implicant construction are in the API

## Example Input

```
(define x::real)
(define y::real)

(assert (/= x y))
(assert (forall (z::real) (=> (> y z) (> x z))))
(ef-solve)
(show-model)
```

## Performance

### Benchmarks

- 9 problems from Cheng et al. 2013, all relatively small:
  - 4 examples related to control (encoded using bitvectors)
  - 5 priority synthesis for distributed systems (pure Boolean)

#### Run time (ms)

Solver	Control				Prio. Synth.				
Cheng	0	0	10	10	20	20	170	2430	6740
Yices	0	0	4	8	4	4	16	96	176

#### Iterations

Solver	Control				Prio. Synth.				
Cheng	2	2	3	7	4	4	18	111	11
Yices	1	1	4	7	1	1	10	68	6

## Hardware Application (Gascón, et al., 2014)

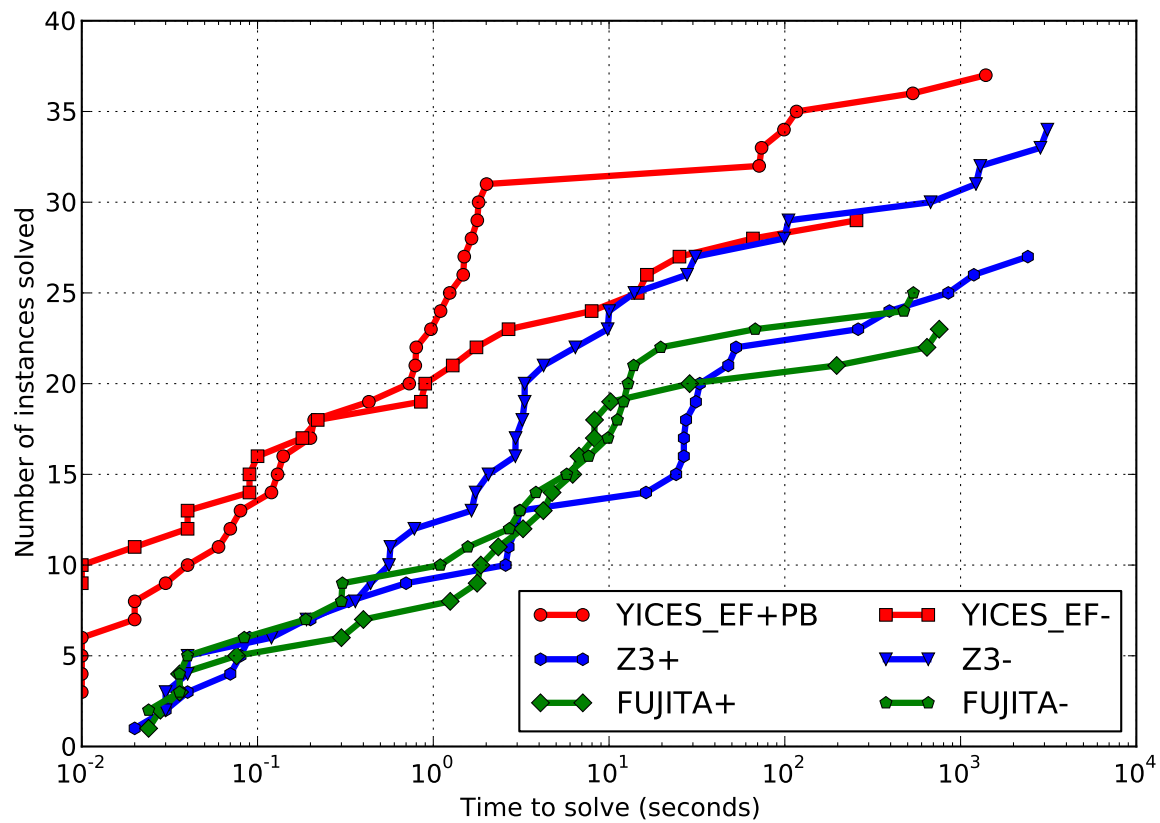
### Reverse Engineering of Hardware

- Check whether a low-level circuit description (netlist) is an instance of a given circuit pattern
- Formulated as an exists/forall problem over bitvectors
- Tested with Yices, Z3, several QBF solvers, and an EF-procedure for 2QBF (Janota and Silva, 2011)

### Results

- Yices and Z3 work best on these benchmarks
- Generic QBF solvers do not work well at all

# Empirical Results



## Program Sketching: Synudic (Tiwari & Gascón)

### Synudic

- Program synthesis framework
- Key idea: **dual interpretation**
  - Basic operations are defined by a signature, an operational, and a *non-operational* semantics
  - The non-operational semantics gives constraints on how operators can be composed
- Uses EF-solving with Yices as a backend
- More details at CADE'2015

<http://www.csl.sri.com/users/tiwari/software/auto-crypto>



## Summary

### Exists/forall Solving

- Easy and useful extension of quantifier-free SMT solving
- The key is to generalize from models
- Given  $y_i$  and  $x_i$  such that  $\neg\Phi(x_i, y_i)$ , we want to remove  $x_i$  and as many other  $x$ -candidates as we can from consideration
- This amounts to computing a formula  $G(x)$  such that
  - $G(x_i)$  is true
  - $G(x) \Rightarrow (\exists y : \neg\Phi(x, y))$

### For Linear Arithmetic

- We can compute a  $G$  efficiently by
  - computing an implicant  $J$  from the model
  - applying quantifier elimination to  $J$  based on virtual term substitution, guided by the model

## Coming Soon

### SMT-LIB Frontend

- we're working on a front-end for LRA and BV that uses standard SMT-LIB 2 syntax

### More Logics

- The next Yices release will include MCSAT and support for non-linear arithmetic (QF\_NRA)
- We'll extend EF-solver to non-linear real arithmetic after that
- We're also planning to support linear integer arithmetic (Cooper's algorithm).